



Let's talk about  
Artificial Intelligence and Robotics!



Silvia Santano *and Pepper*

München, 11.04.2018



## Silvia Santano

- › Robotic Applications developer
- › Programming robots since I was 12
- › At inovex since June 2016

# Agenda

- › Computer Vision
- › Image Recognition
- › Pepper
  - › Softbank Robotics
  - › Characteristics
  - › Usecases
  - › Computer Vision
  - › External services
  - › On-device CV with CNNs

# Agenda

- › Computer Vision
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# Automatic extraction, analysis and understanding of information from images













Humans can recognize objects in images  
with little effort despite of huge variations

For computers, this is still a challenge...

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  - › On-device CV with CNNs

# Image Recognition

Main subfields:

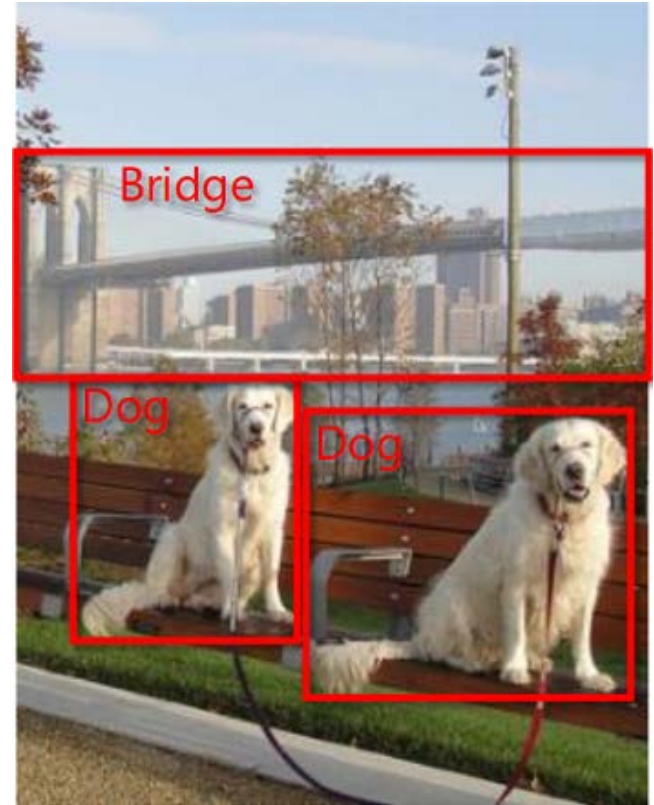
- › **Classification**
- ›› Object detection
- ››› Semantic segmentation



# Image Recognition

Main subfields:

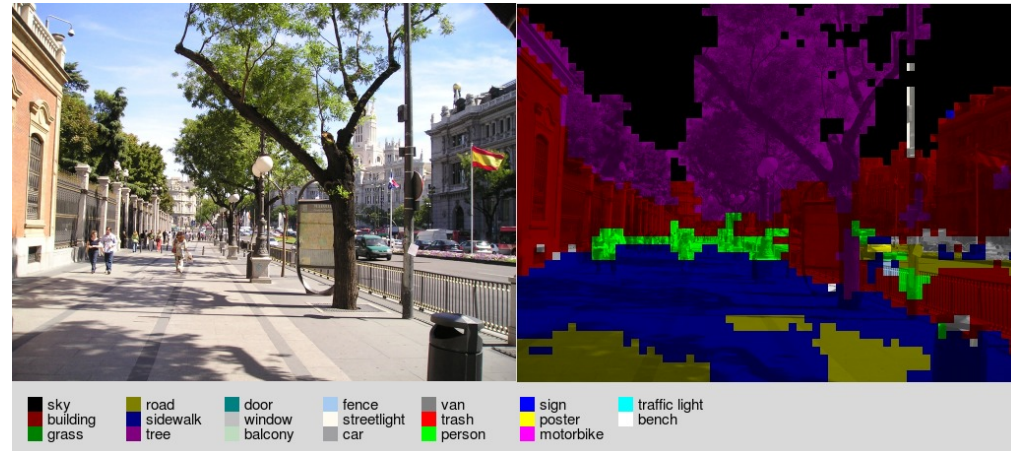
- › Classification
- ›› **Object detection**
- ››› Semantic segmentation



# Image Recognition

Main subfields:

- › Classification
- ›› Object detection
- ››› **Semantic segmentation**



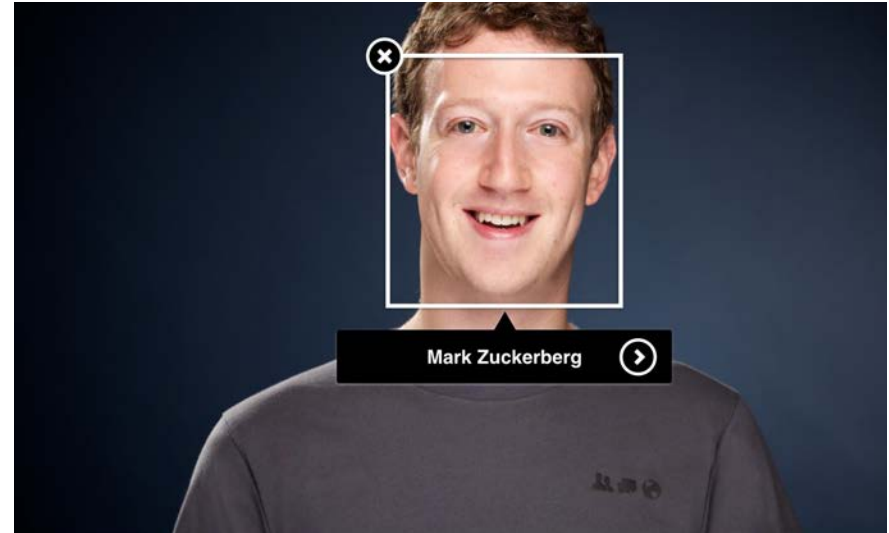


# Image Recognition

Main subfields:

- › Classification
  - ›› Object detection
  - ››› Semantic segmentation

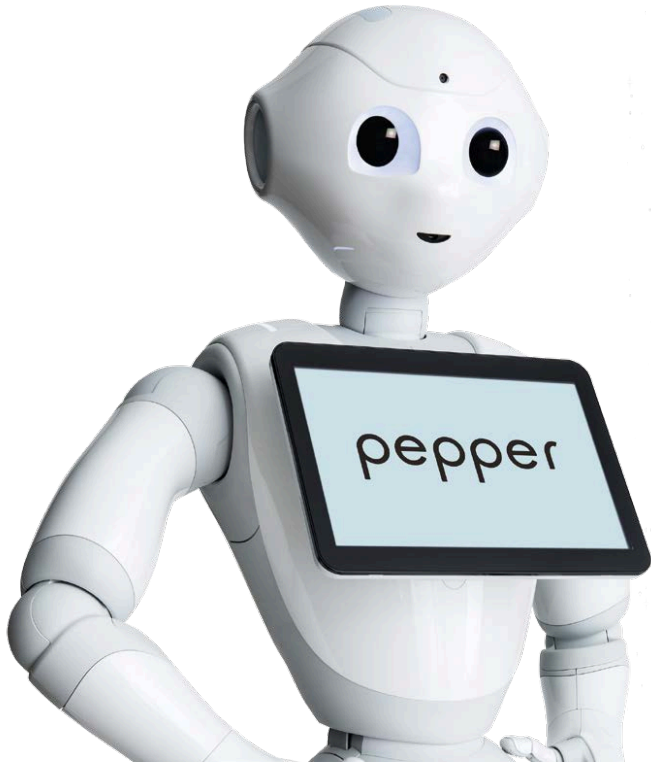
## › Identification



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# Softbank Robotics



- › Leader in Humanoid Robotics
- › Previously: Aldebaran Robotics
- › Headquartered in Paris
- › Creator of NAO, Pepper and Romeo
- › The robots are used in > 70 countries
- › Fields: research, education, retail, healthcare, tourism, hospitality or entertainment, SoftBank
- › **Ecosystem of Certified Partners**



# Softbank Robotics

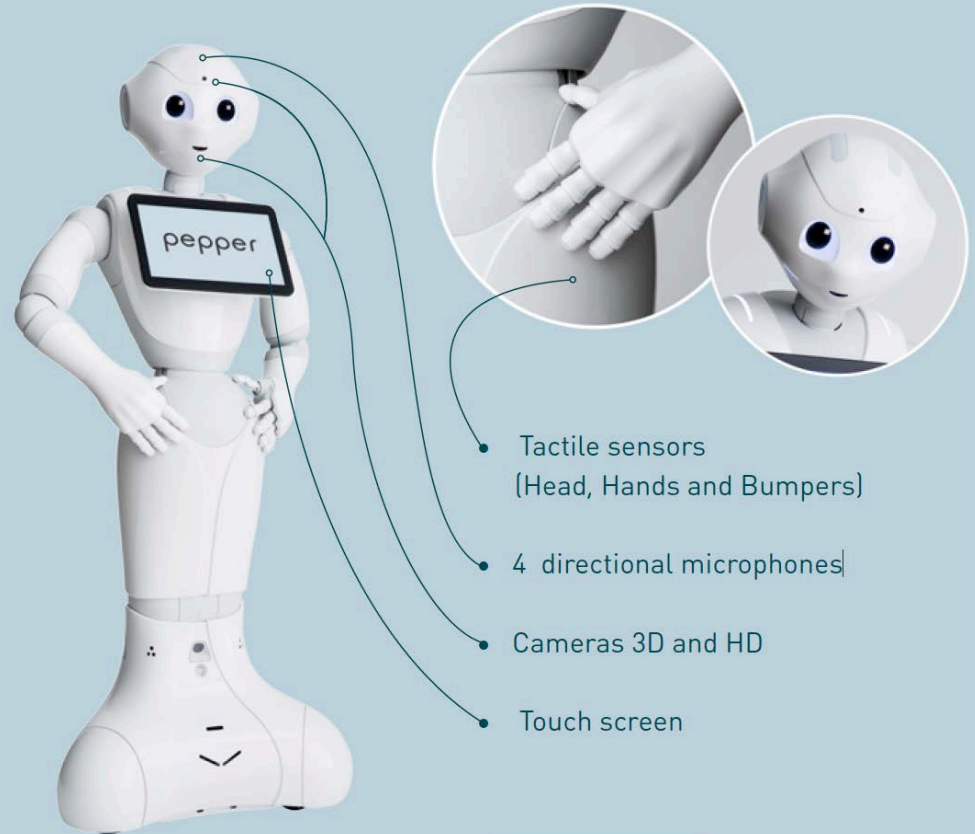


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# Pepper: Technical Characteristics

120 cm  
28 kg  
20° of freedom  
360° movement  
Wi-Fi connection  
12h of autonomy



# Pepper: Technical Characteristics

## Tablet

<b>Processor</b>	Atom E3845
<b>CPU</b>	Quad core
<b>Clock speed</b>	1.91 GHz
<b>RAM</b>	4 GB DDR3
<b>OS</b>	Nao QI OS
<b>Sensors</b>	2 HD Cameras (OV5640) 1 3D Sensor (ASUS XTION) 4 Microphones 3-axis Gyrometer + 3-axis Accelerometer 6 laser line generators 2 Infra-Red sensors 2 ultrasonic sensors 3 tactile sensors 3 bumpers
<b>Motors</b>	20 Motors and actuators

<b>Processor</b>	ARM Cortex-A7
<b>CPU</b>	Quad core
<b>Clock speed</b>	1.3 GHz
<b>RAM</b>	DDR3 SDRAM 1GB (512MB * 2)
<b>Flash Memory</b>	32GB (eMMC)
<b>OS</b>	Android 6.0
<b>Dimensions</b>	246 x 175 x 14.5 mm
<b>Display</b>	Type: IPS, Resolution: 1280*800 Color: 24bit true color
<b>Touch Panel</b>	Capacitive Multi-Touch (5 point)
<b>Sensors</b>	Light illumination, Acceleration Gyro, Geomagnetic

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# So, what can this 'Pepper' actually do?

Pepper is:

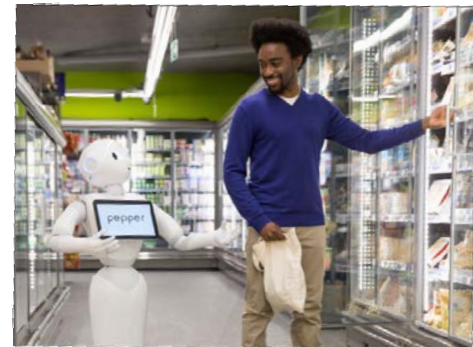
- › Proactive
- › Attractive
- › Interactive
- › Emotional and empathetic
- › Connected
- › Customisable



# So, what can this 'Pepper' actually do?

Usecases:

- › Welcoming
- › Informing and recommending products
- › Guiding
- › Attracting
- › Improving customer knowledge
- › Entertaining
- › ...



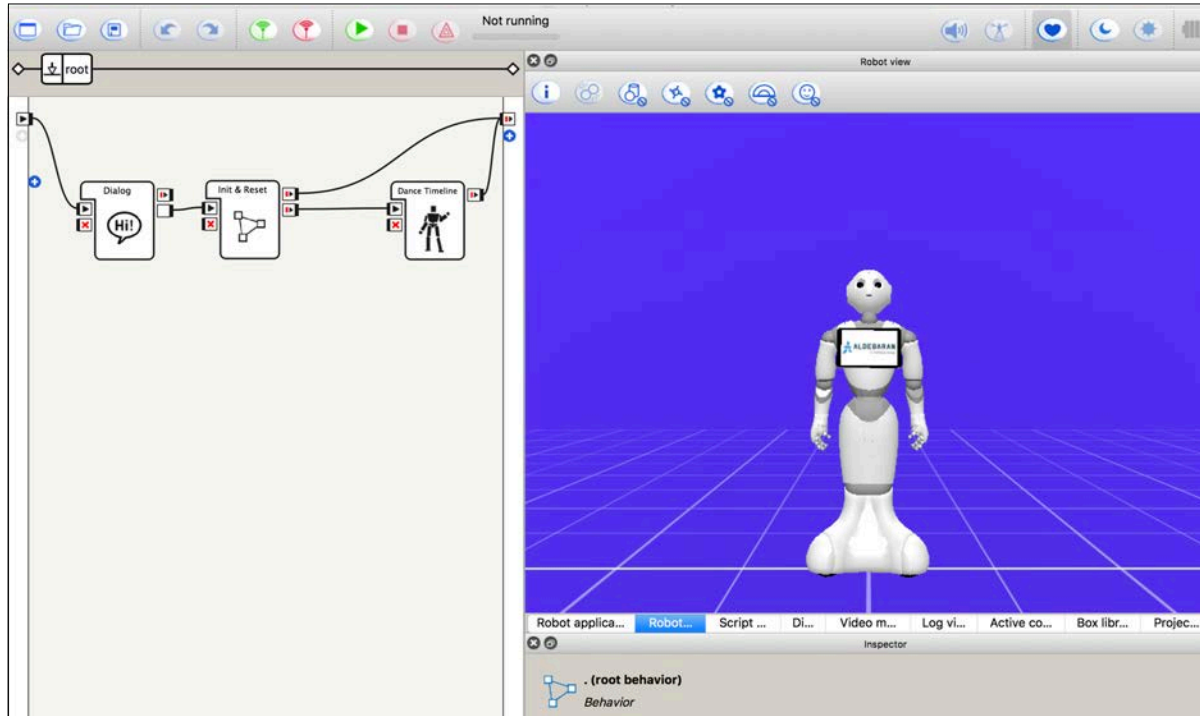
Pepper is still a work in progress...

# How to program Pepper

- › Choregraphe & Python
- › Python SDK
- › C++ SDK
- › Javascript (Tablet)
- › Soon: Android (still reduced function set)
- › QiChat (Dialogs)

# How to program Pepper

## Choregraphe



# How to program Pepper QiChat

```
# Volume
##down
u:([
    "{~can_you} {"ein bisschen" etwas} leiser [sprechen reden]"
    "sprich {"ein bisschen" etwas} leiser"
    "Dreh die Lautstärke runter"
    "sprich nicht so laut"
    "du sprichst zu laut"
])
^gotoReactivate(decrease_volume)
u:($empty) %decrease_volume
^call(ALVolumeSlider.decreaseVolume()) $Demo/back=1
c1:(false) es tut mir leid, das ist das Minimum
c1:(true) okay ich spreche jetzt leiser

u2:([
    nochmal
    mehr
    "noch {"ein bisschen" etwas} mehr"
    "immer noch zu laut"
])
^gotoReactivate(decrease_volume)
```

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# Computer Vision with Pepper

- › Face Detection and People Tracking
- › Face Learning and Recognition
- › People Characteristics Perception



# Computer Vision with Pepper

## People Characteristics Perception

`PeoplePerception/Person/<ID>/AgeProperties`

`PeoplePerception/Person/<ID>/ExpressionProperties`

`PeoplePerception/Person/<ID>/GenderProperties`

`PeoplePerception/Person/<ID>/SmileProperties`

`PeoplePerception/Person/<ID>/FacialPartsProperties`

`PeoplePerception/Person/<ID>/Distance`

`PeoplePerception/Person/<ID>/IsFaceDetected`

`PeoplePerception/Person/<ID>/IsVisible`

`PeoplePerception/Person/<ID>/NotSeenSince`

`PeoplePerception/Person/<ID>/PresentSince`

`PeoplePerception/Person/<ID>/RealHeight`

`PeoplePerception/Person/<ID>/ShirtColor`

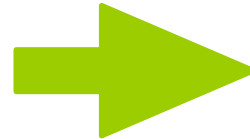
# Computer Vision with Pepper

- › Face Detection and People Tracking
- › Face Learning and Recognition
- › People Characteristics Perception
- › Emotion Recognition

# Computer Vision with Pepper

## Emotion Recognition Module

- › Data sources:
  - › Expression and smile
  - › Acoustic voice emotion analysis
  - › Head angles
  - › Touch sensors
  - › Semantic analysis from speech
  - › Sound level and energy level of noise
  - › Movement detection



```
Valence
Attention Level
Smile
Expression
{
    "calm"
    "anger"
    "joy"
    "sorrow"
    "laughter"
    "excitement"
    "surprise"
}
(Real values normalized)
```

# Computer Vision with Pepper

- › People Tracking
- › Face Detection, Learning and Recognition
- › People Perception
- › Emotion Recognition
- › Vision Recognition
- › Barcode Reader

# Computer Vision with Pepper



**DEMO**

People Perception  
Emotion Recognition  
Face Detection and Recognition

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# External services integration

## Google's Machine Learning Cloud Vision API

- › Machine learning service with pre-trained models
- › JSON REST API / client libraries (C#, GO, Java, Node.js, PHP, Python, Ruby)

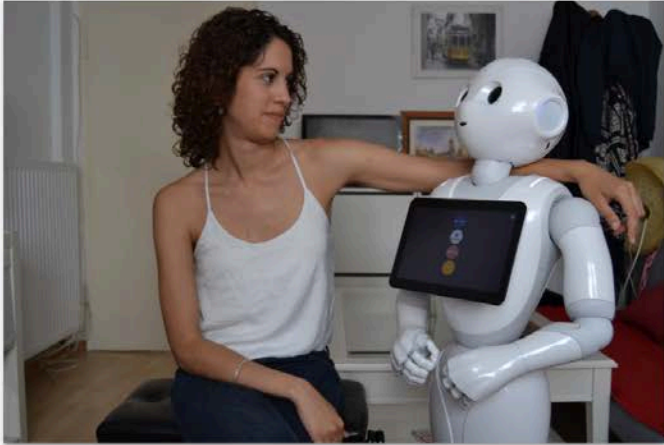
Explicit Content Detection  
Logo Detection  
Label Detection  
Landmark Detection  
Optical Character Recognition  
Face Detection  
Image Attributes  
Web Detection



# External services integration

## Google's Machine Learning Cloud Vision API: LABELS

Navigation tabs: Faces | **Labels** | Web | Properties | Safe Search | JSON



DSC\_2074.JPG

Technology	93%
Room	88%
Shoulder	82%
Arm	73%
Robot	68%
Machine	62%
Product	62%
Electronic Device	59%
Girl	56%



# External services integration

Google's Machine Learning Cloud Vision API: LOGO DETECTION



*Good, but show me the code...*

# External services integration

## Google's Machine Learning Cloud Vision API: LABELS

```
def detect_labels(path):  
    """Detects labels in the file."""  
    client = vision.ImageAnnotatorClient()  
  
    with io.open(path, 'rb') as image_file:  
        content = image_file.read()  
  
    image = types.Image(content=content)  
  
    response = client.label_detection(image=image)  
    labels = response.label_annotations  
    print('Labels:')  
  
    for label in labels:  
        print(label.description)
```

client libraries (C#, GO, Java, Node.js, PHP, **Python**, Ruby)

# External services integration

## Google's Machine Learning Cloud Vision API: LABELS

POST [https://vision.googleapis.com/v1/images:annotate?key=YOUR\\_API\\_KEY](https://vision.googleapis.com/v1/images:annotate?key=YOUR_API_KEY)

```
{
  "requests": [
    {
      "image": {
        "content": "/9j/7QBEUGhvdG9zaG9...base64-encoded-image-content...fXNWzvDE
      },
      "features": [
        {
          "type": "LABEL_DETECTION"
        }
      ]
    }
  ]
}
```

JSON REST API

# External services integration

Google's Machine Learning Cloud Vision API



Logo Detection  
Label Detection  
Optical Character Recognition  
Web Detection  
Emotion Detection

# External services integration

## Microsoft Cognitive Services



- › Machine learning service with pre-trained models
- › JSON REST APIS / client libraries (C#, Android, Swift)

Computer Vision API:

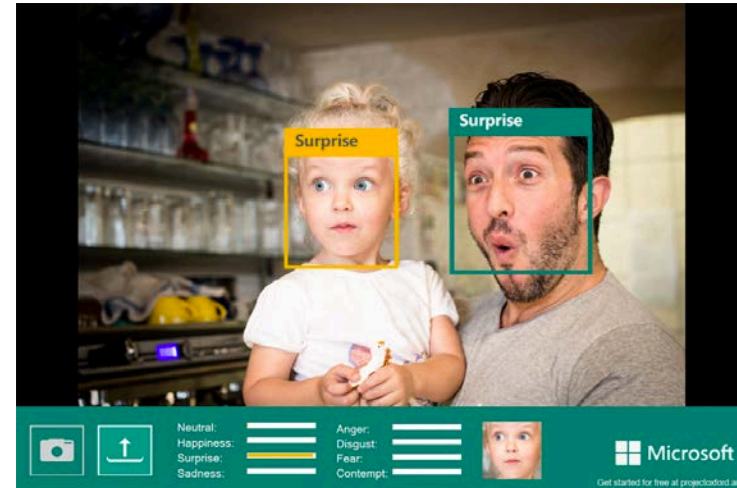
Analyze Image

Optical Character Recognition

Handwritten Text Detection

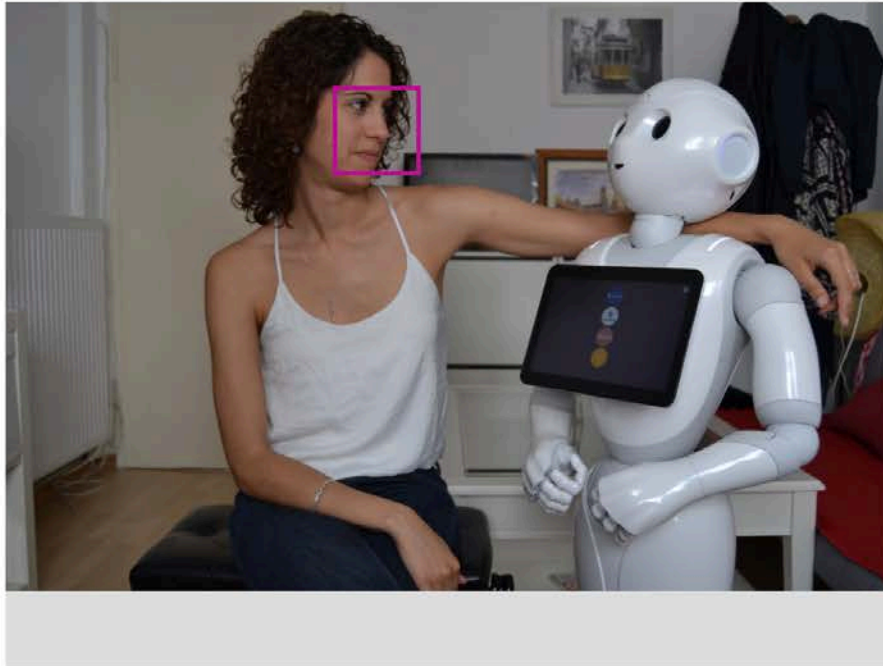
Face API

Emotion API



# External services integration

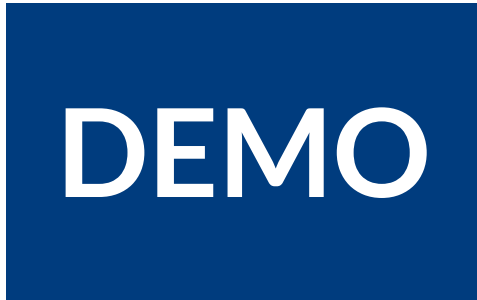
## Microsoft Cognitive Services: COMPUTER VISION API



FEATURE NAME:	VALUE
Description	{ "tags": [ "person", "indoor", "woman", "holding", "man", "front", "table", "white", "black", "standing", "young", "cake", "playing", "dog", "room", "plate", "remote", "kitchen" ], "captions": [ { "text": "a woman standing in front of a cake", "confidence": 0.75387466 } ] }
Tags	[ { "name": "wall", "confidence": 0.996851742 }, { "name": "person", "confidence": 0.996797 }, { "name": "indoor", "confidence": 0.973828435 } ]
Image format	"Jpeg"
Image dimensions	1080 x 1620

# External services integration

Microsoft Cognitive Services



Analyze Image

Optical Character Recognition

Handwritten Text Recognition

Emotion Detection



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# On-device CV with CNNs

## Why

- › Privacy
- › Latency
- › Connectivity
- › Security
- › Cost

# On-device CV with CNNs

## Limitations

- › Compute
- › Memory
- › Storage
- › Power
- › Bandwidth

# On-device CV with CNNs

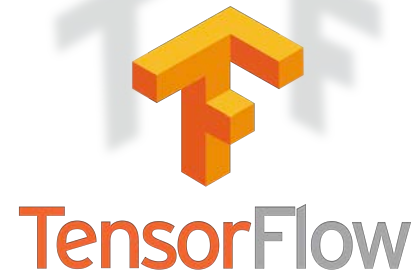
## How



- › e.g. Tensorflow Mobile
- › or Tensorflow Lite

Pre-trained models

Tensorflow Object Detection API



# ...Out of curiosity



Google's Algorithm  
found houses



Google's Algorithm  
found no houses

# Yes, but: chihuahua or muffin?



# Comparison

- › **Amazon's Rekognition** is not just good at identifying the primary object but also the many objects around it
- › **Google's Vision API and IBM Watson Vision** return straightforward, descriptive labels
- › **Microsoft's** tags were usually too high level
- › **Cloudsight** is a hybrid between human tagging and machine labelling. More accurate. Slower. More expensive.
- › **Clarifai** returns, by far, the most tags (at 20) although very generic tags. It also adds qualitative and subjective labels, such as “cute”, “funny”, “adorable”, and “delicious”

Vielen Dank

Silvia Santano  
Application Development

Twitter: @SilviaSantano

LinkedIn: silviasantano

[ssantano@inovex.de](mailto:ssantano@inovex.de)

