

FOSS & Safety

The case of Zephyr

Team inovex

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Solution Architect Medical IoT

#FOSS4MEDICAL

- PhD in Physics (long ago)
- SW/System Architect since 15 years
 - mainly Medical Devices
- Trainer & Technical Consultant
 - SW-Architecture, Zephyr, Yocto
- In Love w/ Zephyr since 2016
 - realised several prototype projects for life-science R&D
 - Maintainer of TiacSys-Bridle Project
 - Participant Zephyr Safety-WG

Agenda for today

- Functional Safety for SW Systems
- Zephyr, FOSS & Functional Safety
- Functional Safety & Beyond



A Functional Safety 101

Definition of Functional Safety

- **Safety** – the freedom from unacceptable risk of **physical injury** or of **damage to the health of people**, either directly, or indirectly as a result of **damage to property or to the environment**
- **Functional Safety**
 - Part of safety that depends on a system or equipment operating correctly in response to its inputs
 - **Detecting potentially dangerous conditions**, resulting either in the activation of a protective or corrective device or mechanisms to **prevent hazardous events** or in providing mitigation measures to **reduce the consequences** of the hazardous event.

Functional Safety



When Software lost its innocence

- Therac-25 was a radiation therapy machine in the 1980s sold by Atomic Energy of Canada Ltd.
- 100x radiation overdose from what operators had intended to apply
- three fatalities and many more injured as a consequence of treatment
- later severe SW design flaws were identified as the root cause for the malfunctioning of the machine



- Read the full story here:

<https://en.wikipedia.org/wiki/Therac-25>

Functional Safety for Software Systems

Therac-25 incidents became possible due to

1. inappropriate development process
 - single Developer doing all coding & testing
 - no risk analysis considering malfunctioning of SW
 - no final integration testing prior to deployment
2. inappropriate user interface
 - obscure error messages
 - operators could simply proceed
3. inappropriate SW design
 - SW-code reuse from previous machines that relied on HW-interlocks which Therac-25 had not
 - arithmetic overflows due to coding errors

```
PATIENT NAME: John
TREATMENT MODE: FIX          BEAM TYPE: E      ENERGY (KeV): 10

                                ACTUAL      PRESCRIBED
UNIT RATE/MINUTE             0.000000    0.000000
MONITOR UNITS                 200.000000  200.000000
TIME (MIN)                    0.270000    0.270000

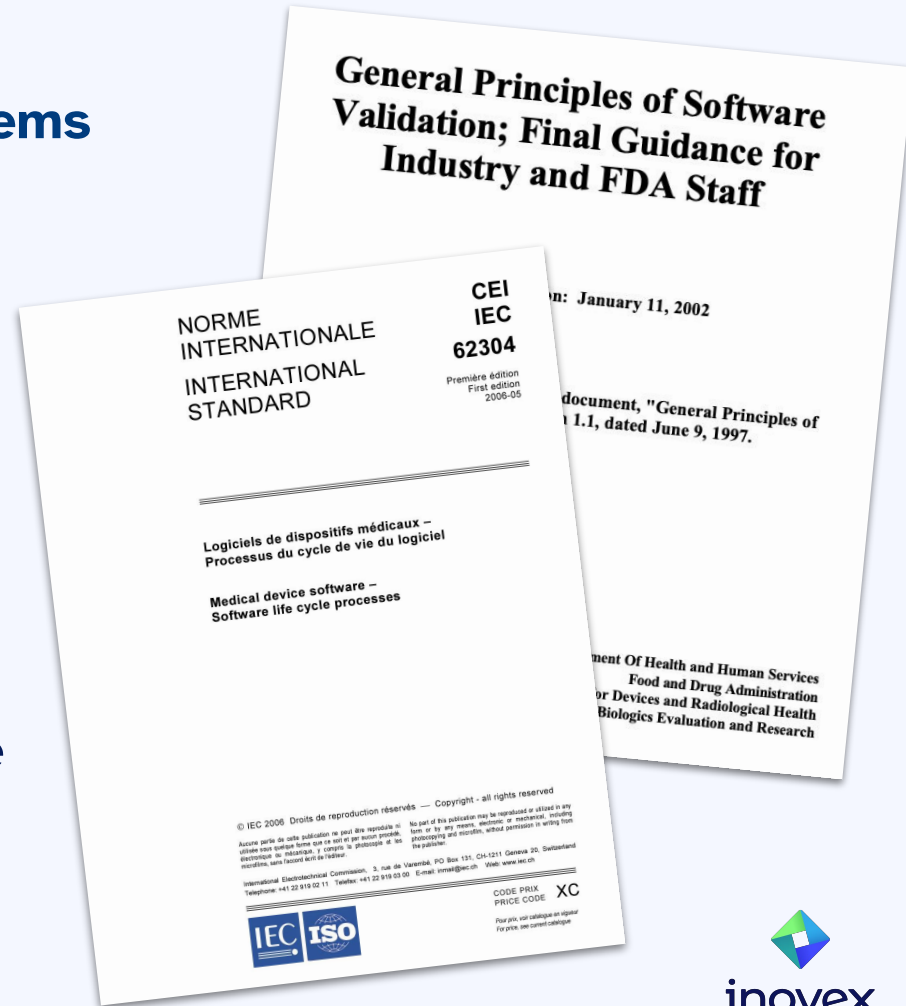
GANTRY ROTATION (DEG)        0.000000    0.000000    VERIFIED
COLLIMATOR ROTATION (DEG)    359.200000  359.200000  VERIFIED
COLLIMATOR X (CM)           14.200000   14.200000   VERIFIED
COLLIMATOR Y (CM)           27.200000   27.200000   VERIFIED
WEDGE NUMBER                 1.000000    1.000000    VERIFIED
ACCESSORY NUMBER             0.000000    0.000000    VERIFIED

DATE: 2012-04-16           SYSTEM: BEAM READY   OP.MODE: TREAT      AUTO
TIME: 11:48:58             TREAT: TREAT PAUSE  X-RAY              173777
OPR ID: 033-cfs3p         REASON: OPERATOR    COMMAND: █
```

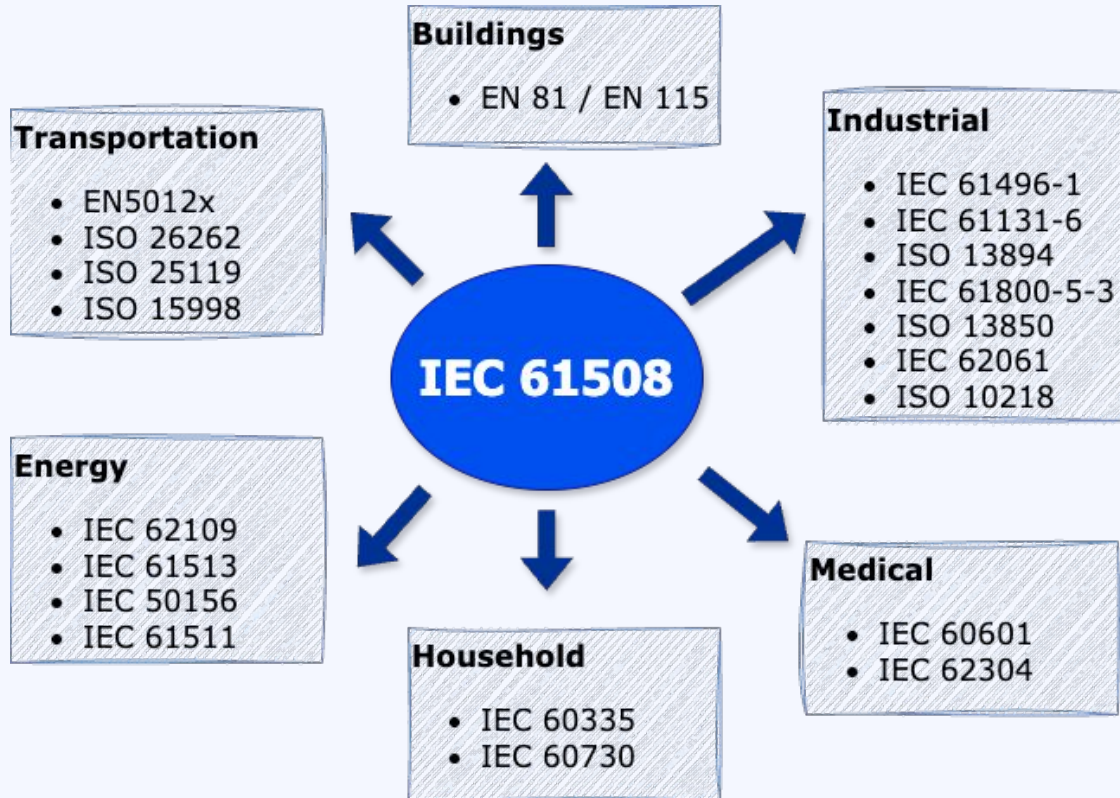

Functional Safety for Software Systems

Therac-25 lead to creation of **IEC 62304** and FDAs “**General Principles of Software for Medical Devices**”

to make sure manufacturers **act responsibly** during the creation of SW that could potentially harm or kill people



The many standards of Functional Safety



What IEC 61508 wants us to do

Think ahead

- Hazard & Risk analysis
- Failure analysis

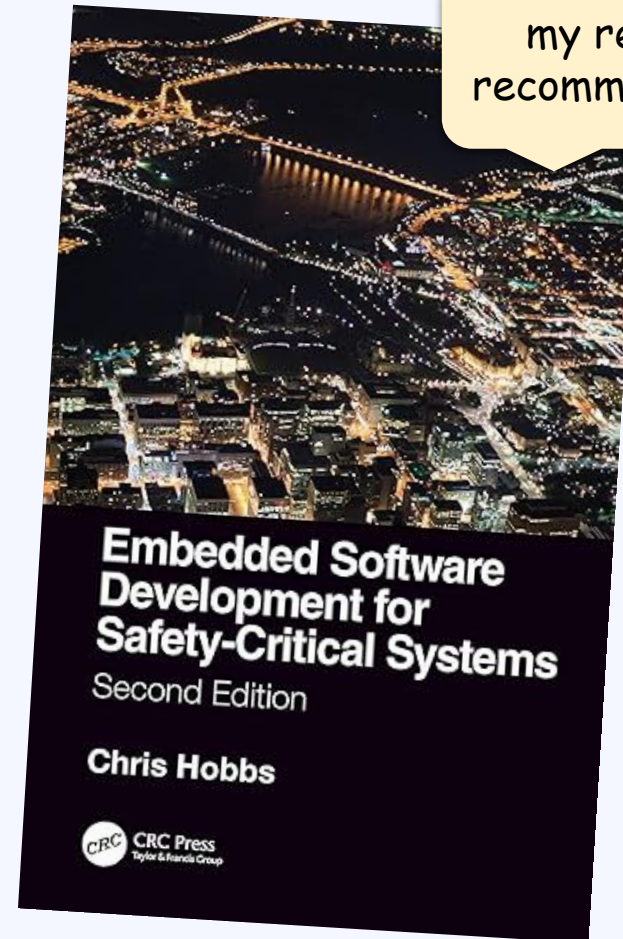
Apply design methodology

- Architect for Safety
- Error Detection & Handling
- Expect the Unexpected
- Redundancy
- Out of scope software elements

Compile Evidence

- SW Verification & Validation
- Safety Case

my reading
recommendation



Sure, but what about SW Security

Security: Protect machines from (maliciously acting) humans

Safety: Protect humans from machines going wild

- Insecure systems most likely un-safe, too
 - e.g. attackers could nullify safety measures to harm people
- Yet, securing systems may introduce safety risks
 - e.g. FOTA updates to mitigate CVEs

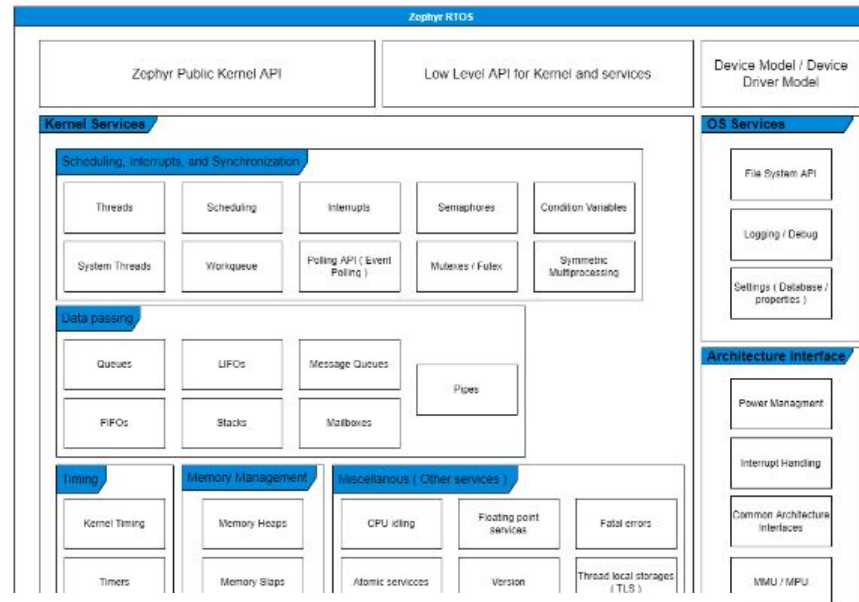


Functional Safety & Zephyr

Safety - Initial certification focus

- Start with a limited scope of kernel functions and interfaces
- Initial target is **IEC 61508 SIL 3 / SC 3**
 - Option for 26262 ASIL D certification has been included in contract with certification authority should there be sufficient member interest
- **Zephyr** to be treated as **Safety Element out of Context (SEooC)**

Scope can be **extended** to include **additional components** with associated **requirements** and **traceability** as determined by the safety committee



Starting scope

Zephyr - systematic capability for Safety

IEC 61508-3, Clause 7.4.2.12

“Where a **pre-existing software element** is **reused** to implement all or part of a safety function, the element shall meet both requirements a) and b) below for systematic safety integrity:

- a) Meet the requirements of one of the following compliance routes:
 - Route 1s: compliant development. Compliance with the requirements of this standard for the avoidance and control of systematic faults in software;
 - Route 2s: proven in use. Provide evidence that the element is proven in use. See 7.4.10 of IEC 61508-2;

 **Route 3s: assessment of non-compliant development. Compliance with**
Zephyr® **7.4.2.13**

Zephyr - systematic capability for Safety

IEC 61508-3, Clause 7.4.2.13

“To comply with Route 3s a pre-existing software element shall meet all of the following requirements a) to i) ... “

- Providing a **safety scope definition**
- Creating **requirements** & establishing **traceability** to code & tests
- Creation of **system- & software specification**
- Definition of the **safety claims**
- Using the existing tests, establishing traceability & enhancing coverage
- Creation of the **safety manual**

Safety Work Product Creation

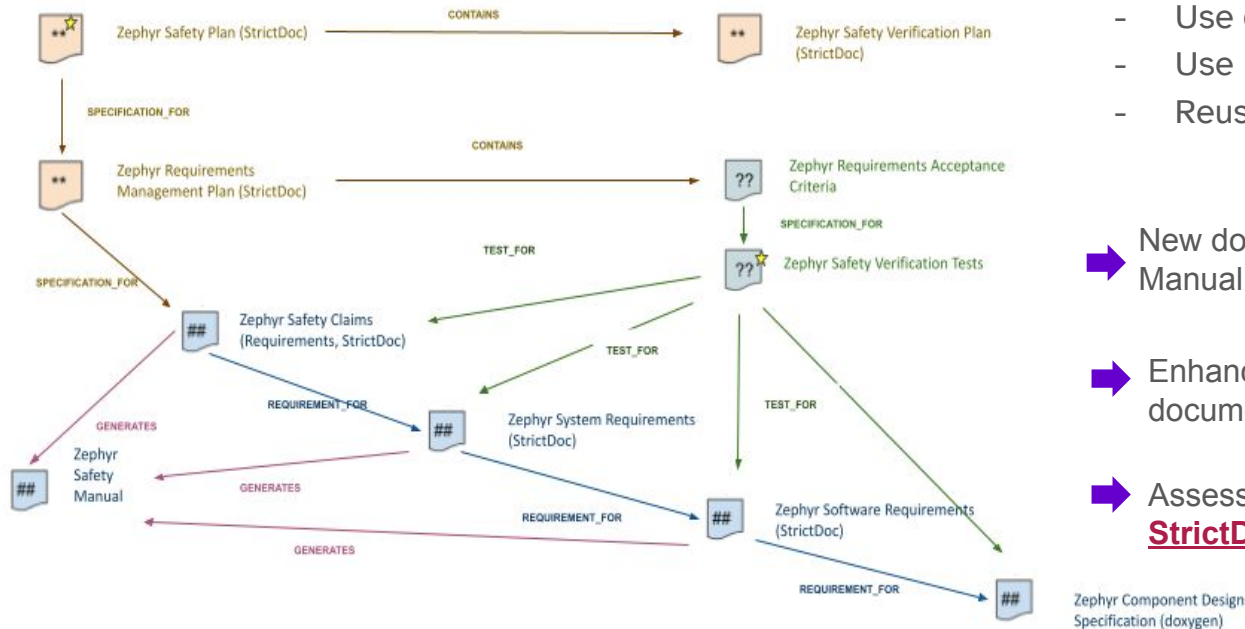
Safety Committee

- Safety Certification strategy decisions
 - Scope of certification
 - Certification standards
 - Certification timeline
- Assessment and audit specific tasks
- Owner of certification artefacts
- Participation limited to the project's platinum members, the safety architect and the functional safety manager

Safety Working Group

- Enabling safety qualifications/certifications in the project
- Working on the creation of the required documentation and evidences
- Setting up requirements management tooling
- creating/deriving and documenting requirements
- Open to everyone to participate

Work Product Structure



Principles for creating the documentation:

- Use **developer friendly** tooling
- Use known workflows on **GitHub**
- Reuse as much as we can from the docs

➔ New documents like Safety Plan, Safety Manual, Requirements: **StrictDoc**

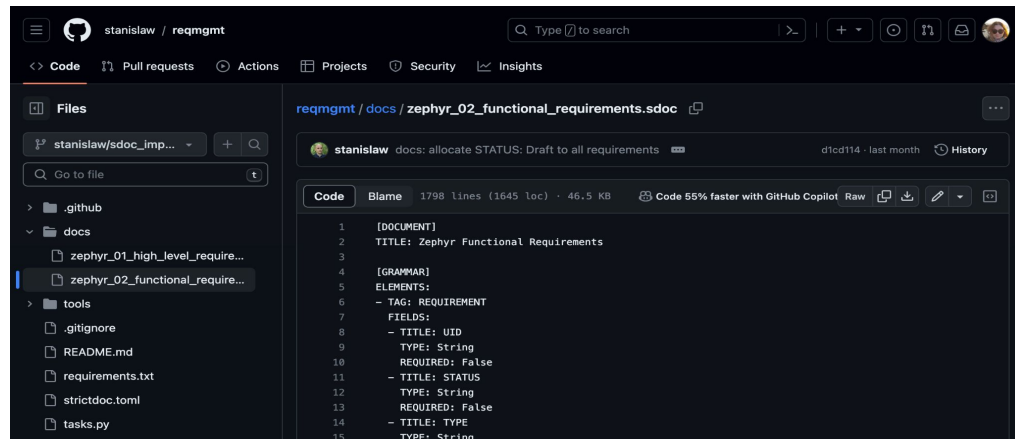
➔ Enhancement of the community documentation in the Docs: **Sphinx**

➔ Assessment evidences & checklist: **StrictDoc**

Zephyr Component Design Specification (doxygen)

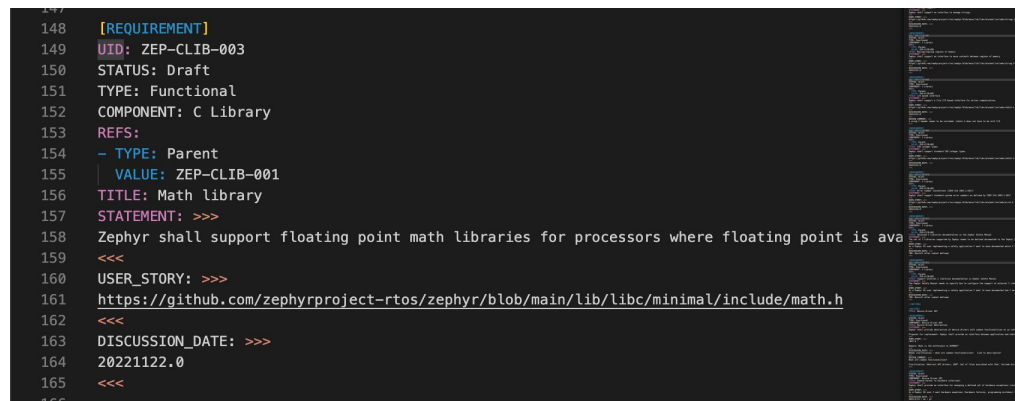
Current requirements work

- Used tooling: StrictDoc (<https://github.com/strictdoc-project/strictdoc>)
- Hierarchical structure of requirements that works for the project
- Capturing the requirements in StrictDoc which is working towards import/export of SPDX



The screenshot shows a GitHub repository named 'reqmgmt' by user 'stanislaw'. The file 'docs/zephyr_02_functional_requirements.sdoc' is open. The file content is as follows:

```
1 [DOCUMENT]
2 TITLE: Zephyr Functional Requirements
3
4 [GRAMMAR]
5 ELEMENTS:
6 - TAG: REQUIREMENT
7   FIELDS:
8   - TITLE: UID
9     TYPE: String
10  - REQUIRED: False
11  - TITLE: STATUS
12    TYPE: String
13  - REQUIRED: False
14  - TITLE: TYPE
15    TYPE: String
```



The screenshot shows a StrictDoc file with a requirement entry. The requirement is as follows:

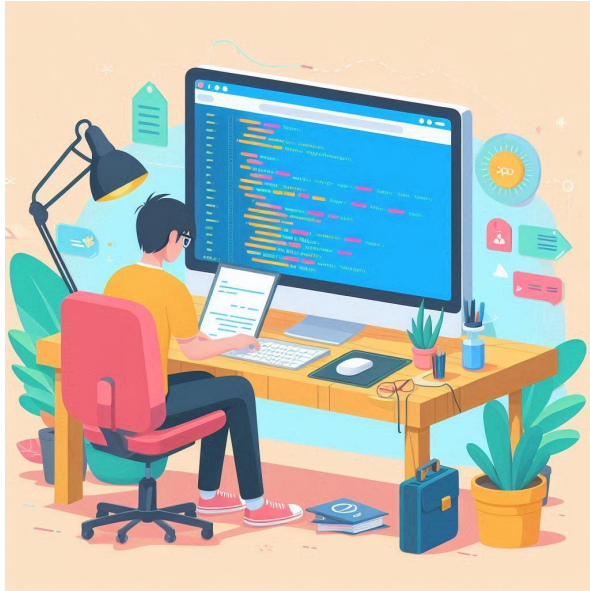
```
148 [REQUIREMENT]
149 UID: ZEP-CLIB-003
150 STATUS: Draft
151 TYPE: Functional
152 COMPONENT: C Library
153 REFS:
154 - TYPE: Parent
155   VALUE: ZEP-CLIB-001
156 TITLE: Math library
157 STATEMENT: >>>
158 Zephyr shall support floating point math libraries for processors where floating point is available.
159 <<<
160 USER_STORY: >>>
161 https://github.com/zephyrproject-rtos/zephyr/blob/main/Lib/libc/minimal/include/math.h
162 <<<
163 DISCUSSION_DATE: >>>
164 20221122.0
165 <<<
```



Also plans, like the Zephyr Safety Plan look like that, each planning item is tracked as a requirement

Assessment checklist -> each checkpoint is a requirement, tracing to the Zephyr's evidences

Compliance with Coding Standards



Project already has defined Coding Guidelines in the docs, based on MISRA

Identification of Coding Guideline violations and adaption of the code

- Initially done by Bugseng on a separate branch
- Recently merged to the main branch

Coming soon: Static Analysis in the CI to check for adherence, powered by Eclair from BUGSENG

Can't wait? Join the Safety Working Group

Write us ...



<https://lists.zephyrproject.org/g/safety-wg>

... talk to us, ask us, ...



<https://discord.gg/mgZkSmq2>

... meet us

WG Video conference (almost) every **Tuesday 4pm CET**

<https://docs.google.com/document/d/1HROTIACp5TpzBdpAXIc2D7zmCvyFsg4NC4WTB5WK3oU/edit#heading=h.s8n3zq5dqe9f>

BTW, security has got a Working Group, too



Read the docs :-)

Safety Overview

Requirements Guideline

The screenshot shows the Zephyr Safety Overview documentation page. The breadcrumb trail is "Docs / Latest » Safety » Zephyr Safety Overview". The page title is "Zephyr Safety Overview" with a version number of 3.7.99. The left sidebar contains a search bar and a navigation menu with items: Introduction, Overview, Safety Document update, General safety scope, Quality, Processes and workflow, Safety Requirements, Samples and Demos, Supported Boards, Shields, Releases, REFERENCE, API, Kconfig Options, and Devicetree Bindings. The main content area has an "Introduction" section with the text: "This document is the safety documentation providing an overview over the safety-relevant activities and what the Zephyr Project and the Zephyr Safety Working Group / Committee try to achieve." and "This overview is provided for people who are interested in the functional safety development part of the Zephyr RTOS and project members who want to contribute to the safety aspects of the project." Below the introduction is an "Overview" section with the text: "In this section we give the reader an overview of what the general goal of the safety certification is, what standard we aim to achieve and what quality standards and processes need to be implemented to reach such a safety certification." The "Safety Document update" section is partially visible at the bottom.

The screenshot shows the Zephyr Safety Requirements documentation page. The breadcrumb trail is "Docs / Latest » Safety » Safety Requirements". The page title is "Safety Requirements" with a version number of 3.7.99. The left sidebar contains a search bar and a navigation menu with items: Security, Safety, Zephyr Safety Overview, Safety Requirements, Introduction, Guidelines, Samples and Demos, Supported Boards, Shields, Releases, REFERENCE, API, Kconfig Options, Devicetree Bindings, and West Projects. The main content area has an "Introduction" section with the text: "The safety committee leads the effort to gather requirements that reflect the actual state of the implementation, following the route 3s approach of the project's safety effort. The goal is NOT to create new requirements to request additional features for the project." and "The requirements are gathered in the separate repository: Requirement repository". Below the introduction is a "Guidelines" section with the text: "Below are the guidelines for the requirements repository and the expectations of the safety committee when adding requirements to the repository." The "Scope" section is partially visible at the bottom with the text: "The scope of the requirements covers the KERNEL functionalities."

Go to our repos

Requirements:

- Grab a PR and give some feedback
- Read through the existing requirements and submit a PR if needed
- Get familiar with [StrictDoc](#)
- Start creating new requirements :-)

Safety Working Group Project:

- Have a look at the tasks
- Grab an existing task
- Or submit a new tasks



<https://github.com/orgs/zephyrproject-rtos/projects/23/views/1>

<https://github.com/zephyrproject-rtos/reqmgmt>

“To boldly go where no man has gone before”

Functional Safety & FOSS - The good ...

- More and more examples where FOSS aims to enter the safety-critical domain
 - XEN Hypervisor
 - ELISA (Embedded Linux in Safety Applications)
 - RTEMS
 - Eclipse ThreadX
 - **Zephyr**



Functional Safety & FOSS - ... the bad & the ugly

In practice several severe Challenges exist towards adoption of FOSS for safety-critical SW

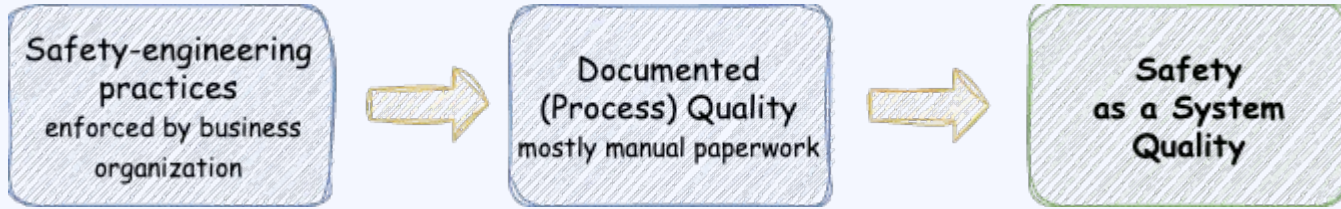
- Non-free standards hamper participation
 - (almost) all ISO/IEC/EC standards
 - MISRA Coding Guidelines
- At their core safety standards are development process standards
 - tailored to fit business/enterprise processes
- Not all stakeholders in a FOSS project do actually care
 - unlike security which is (should be) on everyone's agenda



Check out
<https://www.evs.ee/en/>
most standards for a
reasonable pricee

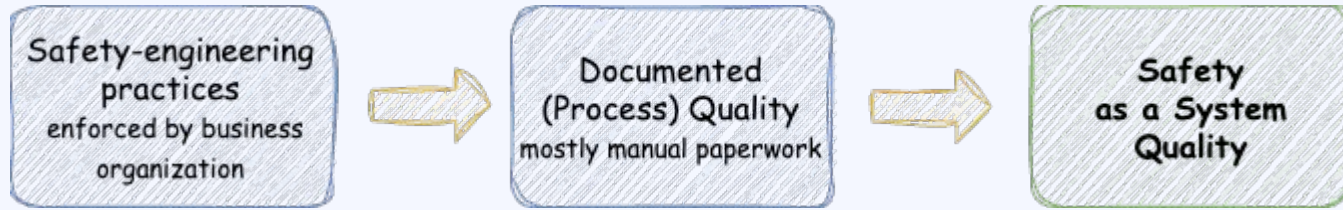


Safety Standards as Process Standards



- works best for **requirements driven** engineering
- however, FOSS better described as **contribution driven** engineering
 - mismatch forces FOSS projects to “backfill” many artifacts
 - extremely challenging to keep up w/ upstream development for these derived artifacts

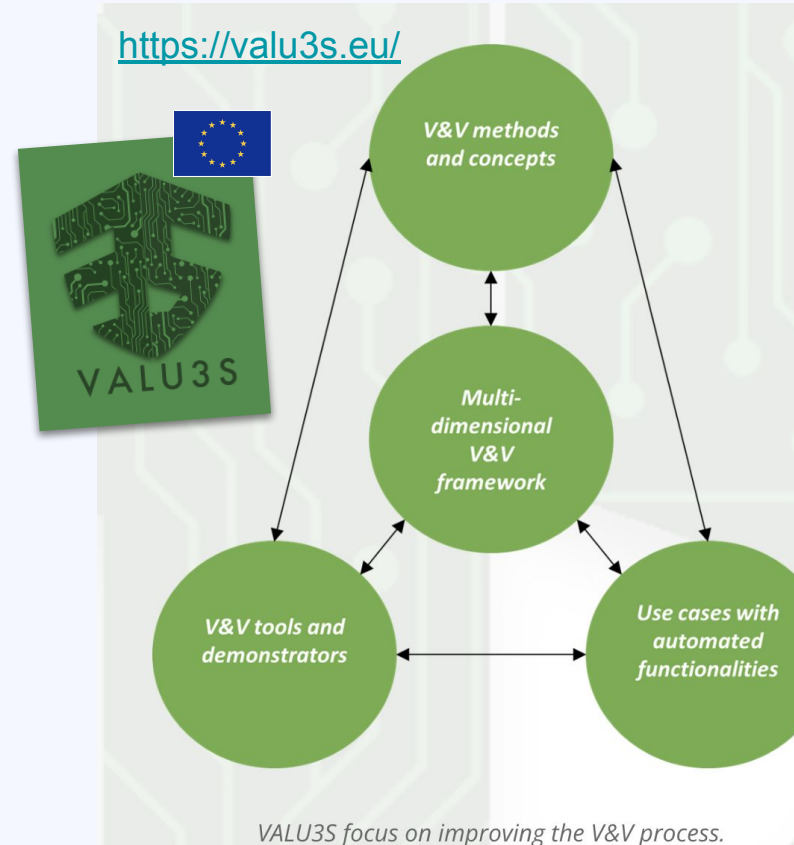
Safety Standards as Process Standards



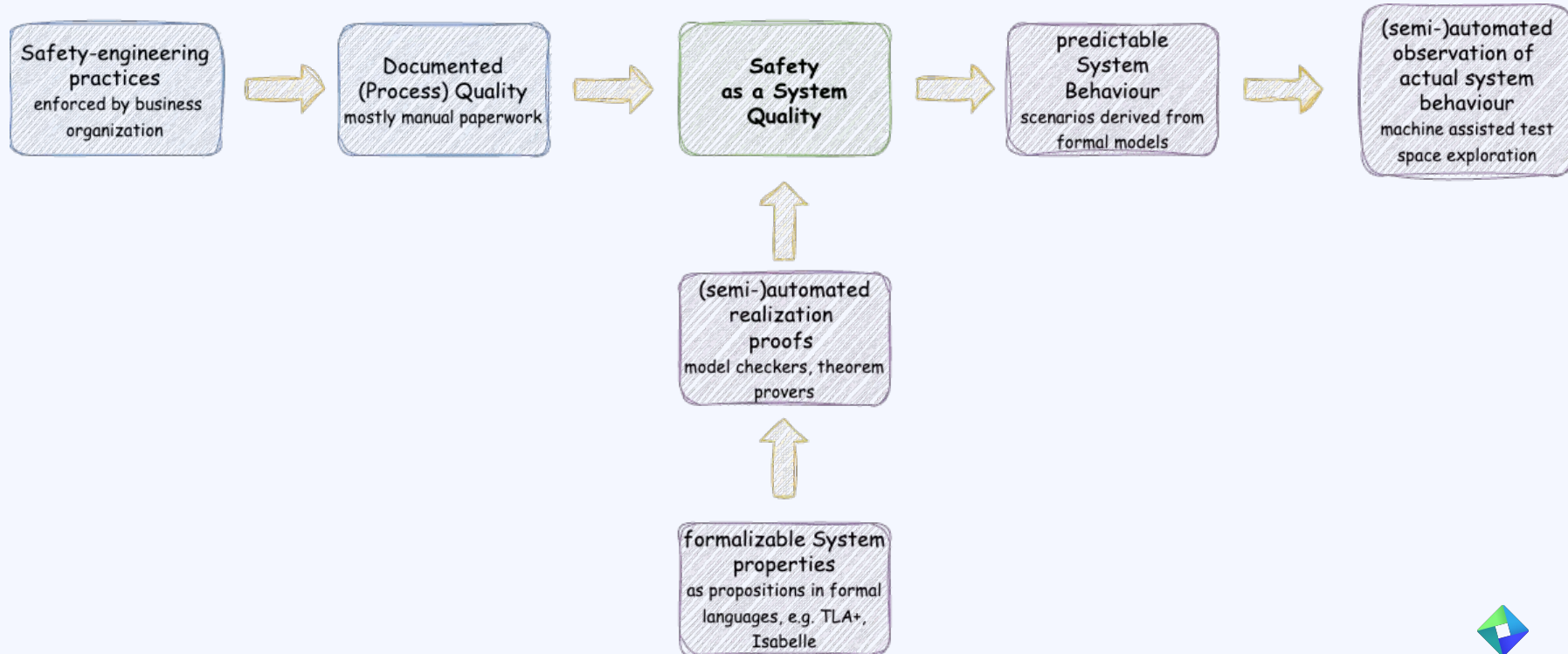
- assumes enforcement by business owners (liability)
- however, FOSS projects have a governance structure (at best)
 - have control over contribution guidelines to reject unsuitable work but no way to mandate “required” work to happen

Rethinking the current approach to functional safety

- Document-driven engineering hitting the complexity-wall anyways
- Rather than chasing the current paradigm boldly help to shape a new paradigm
- Holistic approach to Safety & Security
- Interesting work already available
 - ELISA
 - [STPA](#) (N. Leveson)
 - Formal Methods & Automation



So what to do - Ideas? Anyone?



So what now?

Joint-venture between academia, industries and open source projects/foundations needed

- Many open questions
 - Someone has to figure out what to do and how to do it
- It is going to cost something
 - Someone has to pay the bill
- We share in the sowing, we share in the harvest
 - Someone needs to make sure things work out for the good of all.



Summary

- Software is everywhere, for our own sake we better care for safety & security
- The landscape of safety standards is wide and big
- Zephyr aims to become certified against IEC 61508 as SEooC (Route 3s) at SIL 3
 - Established Safety Committee and Safety Working Group to carry out necessary work
 - Done when it's done, the more the faster
- Need to rethink our approach to functional safety
 - more and more FOSS projects will suffer similar problems



Thank You

Zephyr Hands-On Trainings

starting 2025: Jan 22/23, Apr 02/03, Jul 02/03

Find out more

<https://www.inovex.de/de/training/zephyr-basic-training/>



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